Zum EEPROM (Zowi):

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
| [0] | [1] | [2] | [3] | [4] | [5] | [6] | ... |
| new home for left hip | new home for right hip | new home for left foot | new home for right foot | empty | 1st letter for custom robot name (default value #) | 2nd letter forcustom robot name (default empty) | ... |

Database table columns (local and remote have same structure):

|  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| id | timestamp | serial\_number | e\_left\_hip | e\_right\_hip | e\_left\_foot | e\_right\_foot | state | h\_left\_hip | h\_right\_hip | h\_left\_foot | h\_right\_foot |
| id | time stamp | Zum SN | calibration joint error | calibration joint error | calibration joint error | calibration joint error | OK/NOK | new home position | new home position | new home position | new home position |